



NONLINEAR FORECASTING WITH MANY PREDICTORS BY NEURAL NETWORK FACTOR MODELS

ALI HABIBNIA

DEPARTMENT OF STATISTICS, LONDON SCHOOL OF ECONOMICS



ABSTRACT

- This study proposes a nonlinear generalisation of factor models based on artificial neural networks for forecasting financial time series with many predictors. This model would be able to capture both non-linearity and non-normality of a high-dimensional dataset.
- Specification (architecture) of the neural network factor model is determined on the basis of statistical inference and special emphasis is given to data-driven specification.
- Linear factor models can be represented as a special case of this neural network factor model. It means that, if there is no non-linearity between variables, it will work like a linear model.

CONSTRUCTION OF FNN

Based on the universal approximation theorem, a single hidden layer feedforward network can approximate arbitrary well any continuous function of n real variables. To show that the neural network models can be seen as a generalization of linear models, we allowed for direct connections from the input variables to the output layer and we assumed that the output transfer function $\{\phi_o(\cdot)\}$ is linear, then the model becomes

$$y_t = \beta_o + \sum_{i \rightarrow o} w_{io} x_{it} + \sum_{j \rightarrow o} w_{jo} \phi_j \left(\beta_j + \sum_{i \rightarrow j} w_{ij} x_{it} \right) + \varepsilon_t,$$

Studies in time series widely used the conventional feedforward neural network trained with the backpropagation algorithm, however, the backpropagation is not an efficient algorithm and it converges slowly. Therefore, Levenberg-Marquardt algorithm and its optimized version with LASSO are implemented in this study which are fast and have stable convergence.

RESULTS

Out-of-sample forecast evaluation results based on different criteria (RMSE, Hit-Rate and Theil) showed that the proposed neural network factor model (NNFM) significantly outperformed linear factor model and Random-Walk approach.

INTRODUCTION

Forecasting with factor models are a two-step process:

- **Factor Estimation**, which summarizes the information contained in a large data set in a small number of factors.

$$X_{it} = \Lambda_i f_t + \xi_{it} \quad (1)$$

observations factors idiosyncratic

- **Forecasting Equation**, which is the prediction of the variable of interest by using common factors.

$$y_{t+1|t} = \lambda f_{t+1|t} + \varepsilon_{t+1} \quad (2)$$

one of the X

Common factors and the idiosyncratic component can be forecast simultaneously or separately.

FINANCIAL FORECASTING

Financial returns present special features and share the following stylised facts: comovements, non-linearity, non-gaussianity (skewness and heavy tails) and leverage effect, which makes the modelling of this variable hard.

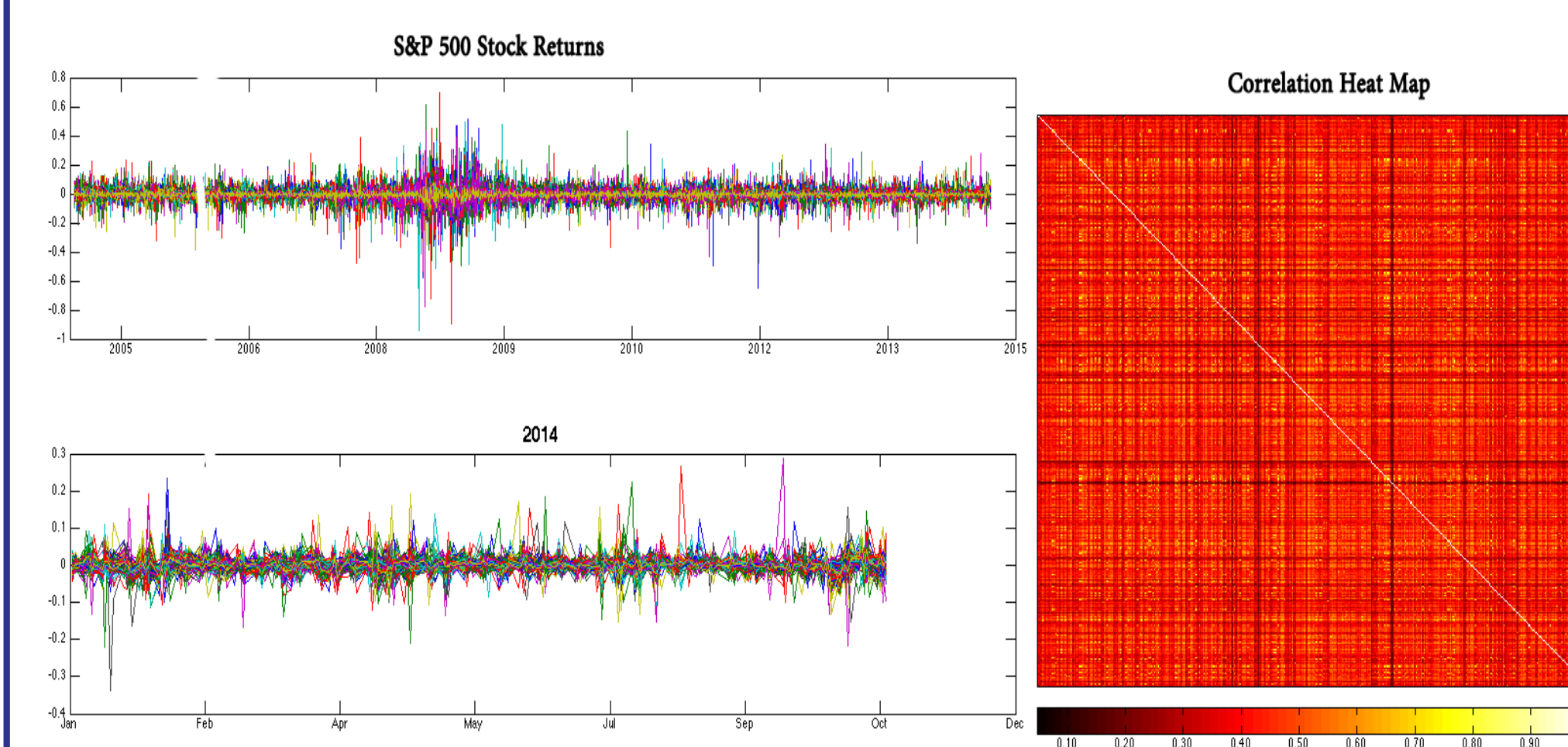


Figure 4: Daily return observations of the 419 companies in S&P500 index

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CONTRIBUTION & FORMULATION

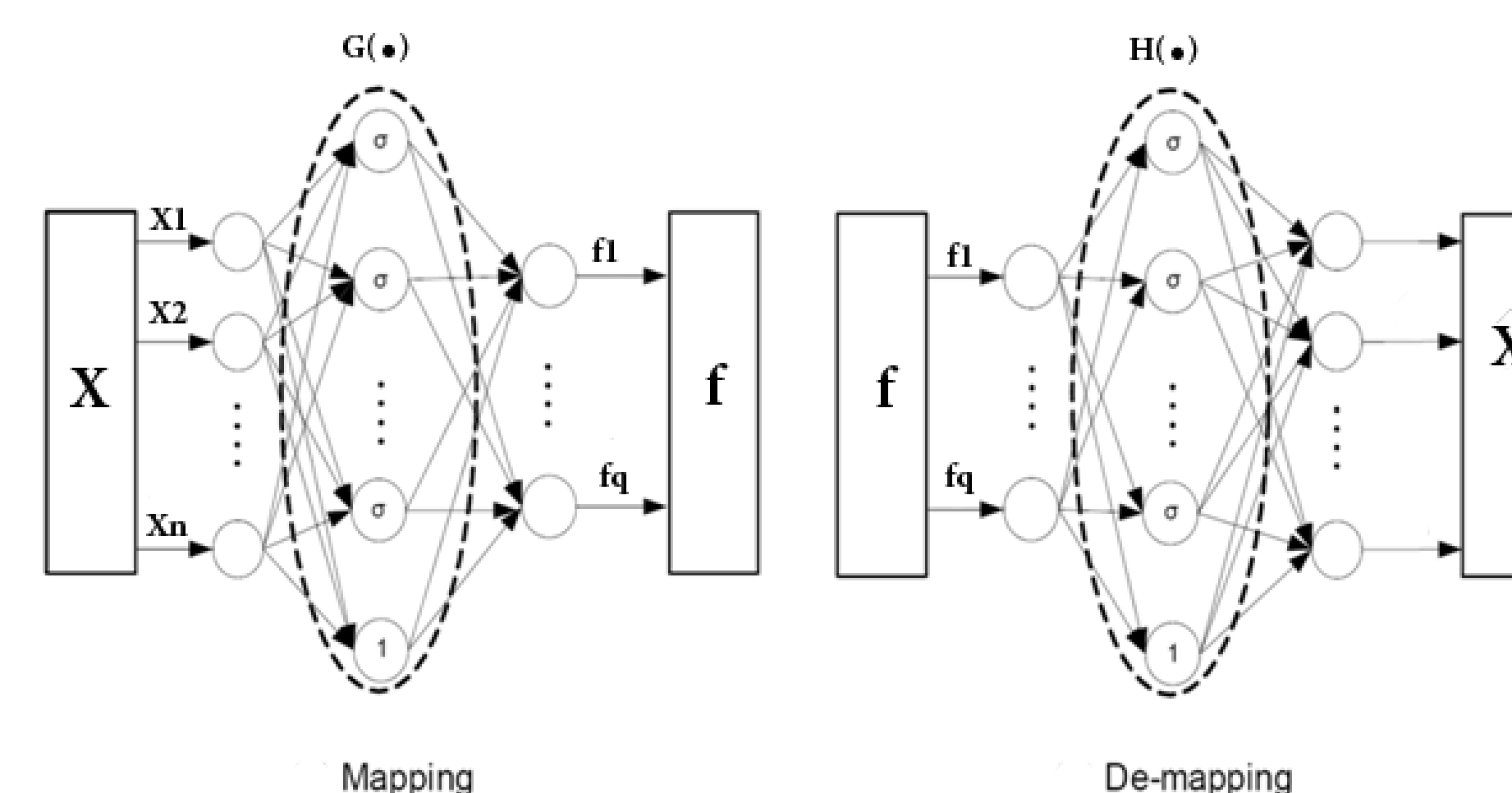


Figure 1: The standard auto-associative neural network architecture for nonlinear PCA (combination of two feed-forward NNs)

- Second extension is a nonlinear factor augmented forecasting equation based on a feed-forward neural network model which can be built in a similar fashion as a statistical model.

$$y_t = \phi_o \left[\beta_o + \sum_{h \rightarrow o} w_{ho} \phi_h \left(\dots \phi_j \left(\beta_j + \sum_{i \rightarrow j} w_{ij} x_{it} \right) \right) \right] + \varepsilon_t,$$

- where x_{it} is the value of the i th input node. $\phi_h(\cdot)$, $\phi_j(\cdot)$ and j, h are activation functions (commonly used function is a sigmoidal function) and number of nodes (neurons) used at the hidden layers.

NLPCA ON FINANCIAL RETURNS

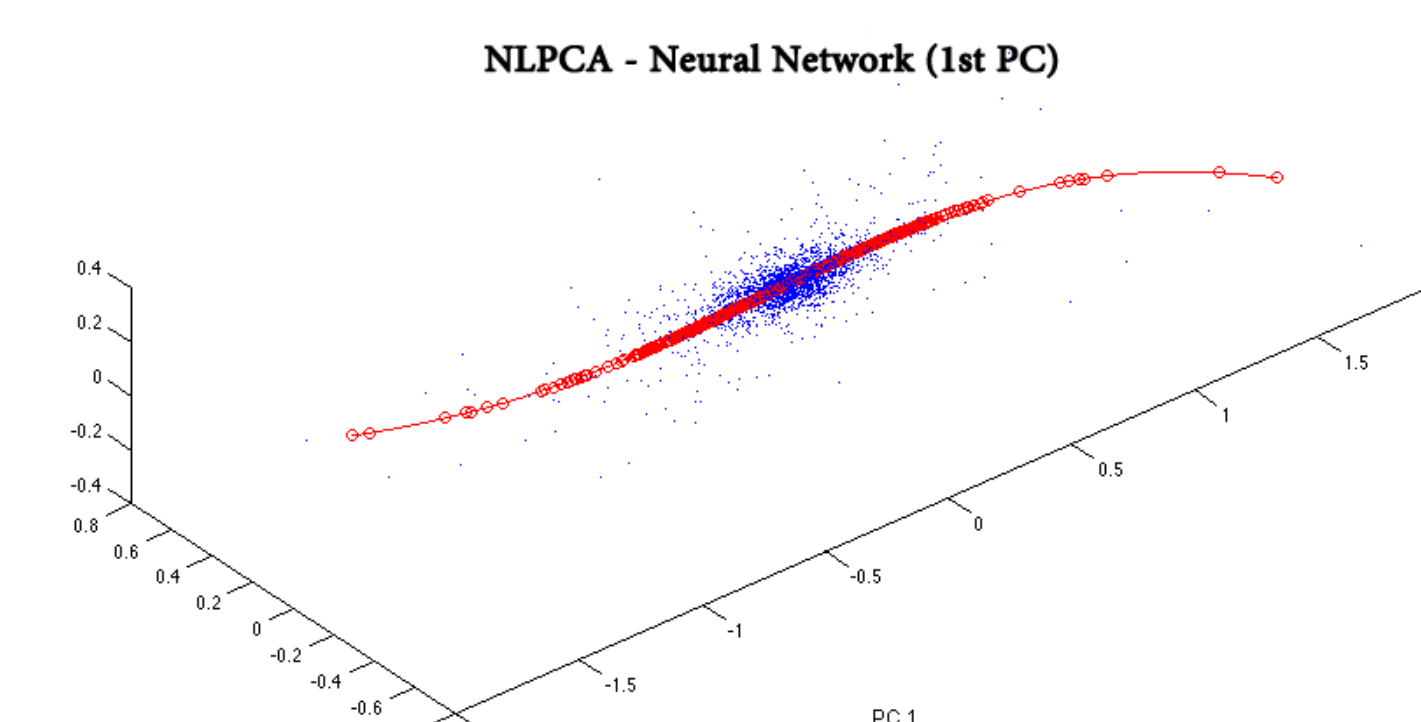


Figure 3: Nonlinear PCA can describe the inherent structure of the data by a curved subspace.

The first extension proposes a **NLPCA (neural network principal component analysis)** as an alternative for factor estimation, which allows the factors to have a nonlinear relationship to the input variables. NLPCA nonlinearly generalizes the classical PCA method by a nonlinear mapping from data to factors. Both neural network parameters and unobservable factors (f) can be optimised simultaneously to minimise the reconstruction error e :

$$e = \hat{X} - X, \quad MSE = E(\|\hat{X}(f) - X\|^2)$$

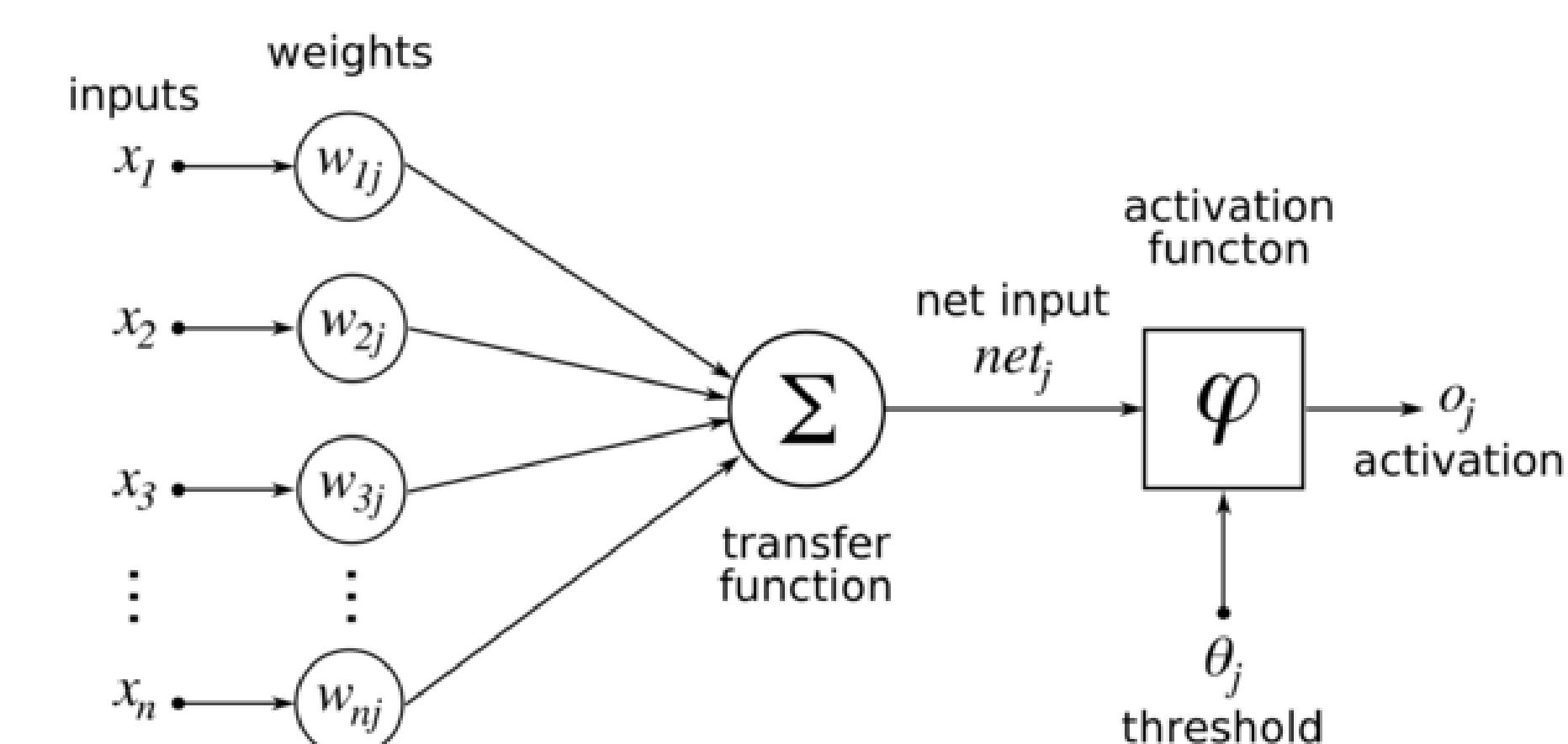
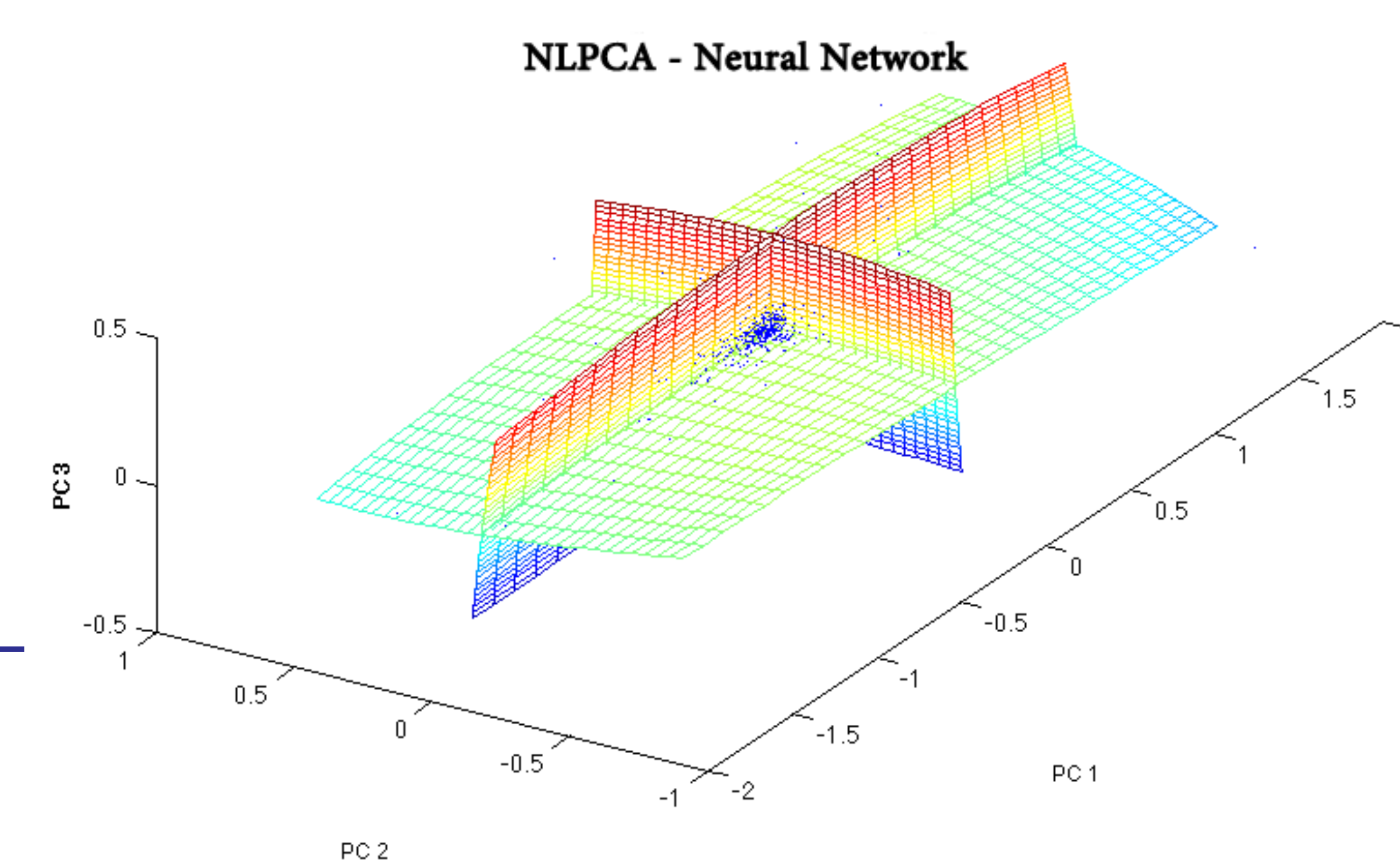


Figure 2: Artificial Neuron configuration



CONTACT INFORMATION

Web <http://personal.lse.ac.uk/habibnia/>
Email a.habibnia@lse.ac.uk
Phone +44 (0)7737842985