

Goal

Transfer an emotion to an input with continuous control



Input space $\mathcal{X} = \mathbb{R}^d$, emotion space $\Theta \subset \mathbb{R}^p$. Build

 $h: \mathfrak{X} \times \Theta \mapsto \mathfrak{X}$, or equivalently $h: \mathfrak{X} \mapsto (\Theta \mapsto \mathfrak{X})$

Empirical Risk $\mathcal{R}_{\mathcal{S}}(h)$

Training samples $(x_{ij}, \theta_{ij}^{out}, y_{ij})_{i \in [n], j \in S_i}$

- $x_{ij} \in \mathcal{X}$ corresponds to an object with input style $\theta_{ij}^{in} \in \Theta$
- $y_{ij} \in \mathcal{X}$ is the same object with output style $\theta_{ij}^{\text{out}} \in \Theta$
- For each object $i \in [n]$ we have access to $|S_i|$ style transition pairs $\left\{ \left(\theta_{ij}^{\text{in}}, \theta_{ij}^{\text{out}}\right) \right\}_{j \in S_i}$
- $\ell = \frac{1}{2} \| \cdot \|_{\mathcal{X}}^2$ is the square loss

$$\mathcal{R}_{\mathcal{S}}(h) := \frac{1}{n} \sum_{i \in [n]} \frac{1}{|S_i|} \sum_{j \in S_i} \ell\left(\begin{array}{c} \underbrace{h\left(x_{ij}\right)\left(\theta_{ij}^{\text{out}}\right)}_{\text{input}}, \underbrace{\theta_{ij}^{\text{out}}}_{\text{object}} \\ \underbrace{\theta_{ij}^{\text{out}}}_{\text{object}}, \underbrace{\theta_{ij}^{\text{out}}}_{\text{object}} \end{array}\right)$$

Problem Formulation in vv-RKHSs

Extension of kernel methods to handle vector-valued outputs [1].

- $k_{\mathcal{X}}: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ and $k_{\Theta}: \Theta \times \Theta \to \mathbb{R}$ two scalar-valued kernels
- $\mathbf{A} \in \mathbb{R}^{d \times d}$ encoding similarities in the outputs
- $G = k_{\Theta} \mathbf{A}, \ K = k_{\mathfrak{X}} \mathrm{Id}_{\mathcal{H}_G} \text{ so that } h : \underbrace{\mathfrak{X} \mapsto (\Theta \mapsto \mathfrak{X})}_{\in \mathcal{H}_K}$
 - $\min_{h \in \mathcal{H}_{K}} \mathcal{R}_{\mathcal{S}}(h) + \frac{\lambda}{2} \|h\|_{\mathcal{H}_{K}}^{2}, \quad \lambda > 0$

Continuous Emotion Transfer Using Kernels

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Optimization

Lemma 1 (Representer) Problem (1) has a unique solution \hat{h} and it takes the form

$$\hat{h}(x)(\theta) = \sum_{i=1}^{t} \sum_{j=1}^{m} k_{\mathcal{X}}(x, x_i) k_{\Theta}(\theta, \theta_{ij}) \mathbf{A} \hat{c}_{ij}, \quad \forall (x, \theta) \in \mathcal{X} \times \Theta$$

for some coefficients $\hat{c}_{ij} \in \mathbb{R}^d$ with $i \in [t]$ and $j \in [m]$.

• t depends on the number of style transition pairs $\{(\theta_{ij}^{\text{in}}, \theta_{ij}^{\text{out}})\}_{j \in S_i}$. (Almost) Closed-form Solution: Reshaping the coefficients in a matrix $\hat{\mathbf{C}} \in \mathbb{R}^{tm \times d}$ yields the Sylvester equation

$$\hat{\mathbf{KCA}} + tm\lambda\hat{\mathbf{C}} =$$

where $\mathbf{K} \in \mathbb{R}^{tm \times tm}$ is the gram matrix of the problem. When $\mathbf{A} = \mathbf{I}_d$ (identity matrix of size $d \times d$), the solution is analytic:

 $\hat{\mathbf{C}} = \left(\mathbf{K} + tm\lambda\mathbf{I}_{tm}\right)^{-1}\mathbf{Y}.$

Representation Choices

• Extract landmarks from face images (KDEF, RaFD datasets), $\chi =$ \mathbb{R}^{136}



• Represent emotions on a compact space $\Theta \subset \mathbb{R}^p$, e.g. Valence-Arousal representation when p = 2 [2].



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(1)

Quantitative Results

Comparison of vITL (ours) against StarGAN [3] in MSE on test set. Two scenarii depending on the observed θ^{in} : single emotional input θ_0 or joint model.

parameters and λ chosen through cross-validation.



• Given a face x, able to generate the trajectory $\theta \to \hat{h}(x)(\theta)$.

Code Available https://github.com/allambert/torch_itl

[1] Carmeli, Claudio and De Vito, Ernesto and Toigo, Alessandro and Umanitá, Veronica Vector valued reproducing kernel Hilbert spaces and universality. In Analysis and Applications, vol 8 pp 19–61, 2010. [2] Russell, James A A circumplex model of affect. In Journal of Personality and Social Psychology, pp. 1161–1178, 1980. [3] Choi, Yunjey and Choi, Minje and Kim, Munyoung and Ha, Jung-Woo and Kim, Sunghun and Choo, Jaegul. StarGAN: Unified Generative Adversarial Networks for Multi-domain Image-to-Image Translation. In Conference on Computer Vision and Pattern Recognition (CVPR), pp. 8789–8797, 2018.

Experimental setup: k_{χ} , k_{Θ} are Gaussian kernels, $\mathbf{A} = \mathbf{I}_d$, kernel

KDEF frontal	RaFD frontal
0.010 ± 0.001	0.009 ± 0.004
0.010 ± 0.001	0.010 ± 0.005
0.012 ± 0.002	0.010 ± 0.005
0.012 ± 0.001	0.010 ± 0.004
0.011 ± 0.001	0.010 ± 0.004
0.011 ± 0.001	0.009 ± 0.004
0.010 ± 0.001	0.011 ± 0.006
0.011 ± 0.001	0.007 ± 0.001
0.029 ± 0.003	0.024 ± 0.007